MATH 221–01 (Kunkle), Exam 1 100 pts, 75 minutes

Name: _____ Feb 7, 2023

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No notes, books, electronic devices, or outside materials of any kind.

Read each problem carefully and simplify your answers.

Unless otherwise indicated, supporting work will be required on every problem worth more than 2 points.

You are expected to know the values of all trig functions at multiples of $\pi/4$ and of $\pi/6$.

1a(8 pts). Sketch the graph of $x^2 - y^2 - z^2 = 8$ on the axes provided.

Label the axes x, y, z however you like, but indicate the positive direction in each variable so that the x-, y-, and z-axes form a right-handed system.

1b(7 pts). How does the graph of $x^2 - 6x - y^2 - 4y - z^2 = 3$ compare to the graph above? Specifically, what can you do the surface $x^2 - y^2 - z^2 = 8$ to obtain the graph of $x^2 - 6x - y^2 - 4y - z^2 = 3$?

Please refer to the positive/negative x-, y-, or z-directions rather than use words like "forward, backward, left, right, ..."

2. Find the following, if they exist.

When asked for a point, give its coordinates; for line, give a parametrization; for a plane or sphere, give an equation.

a(5 pts). The sphere centered at (-2, 1, 3) and tangent to the yz-plane.

- b(5 pts). The line of intersection of the planes 2x y + z = 0, x + y = 1.
- c(7 pts). The plane containing the point (1, 2, 0) and the line (1 t, 1 + 3t, -2t).
- d(9 pts). The points of intersection of the curve $\langle 2t, \sin(\pi t), \cos(\pi t) \rangle$ and the surface $x^2 y^2 z^2 = 8$.
- e(3 pts). The line tangent to the curve parametrized by $\mathbf{r}(t)$ at the point corresponding to t = 1, if

$$\mathbf{r}(1) = \langle 1, 2, 0 \rangle$$
$$\mathbf{r}'(1) = \langle 0, 3, 4 \rangle$$

3(29 pts). Find the following at t = -1 if $\mathbf{r}(t) = \langle t^2, t^2, \frac{1}{3}t^3 \rangle$.

a. $\frac{d\mathbf{r}}{dt}$ and $\frac{d^2\mathbf{r}}{dt^2}$ b. **T**, **N**, **B** c. κ d. a_T and a_N 4(16 pts). Let $\mathbf{u} = \langle 1, -2, 2 \rangle$ and $\mathbf{v} = \langle 3, 6, 2 \rangle$. Find the following, if they exist.

a. $2\mathbf{u} - \mathbf{v}$

b. $|\mathbf{u}|$

- c. a unit vector parallel to \mathbf{u}
- d. the cosine of the angle between \mathbf{u} and \mathbf{v} .
- e. the vector projection of \mathbf{u} onto \mathbf{v} .

5(11 pts). Find the length of the curve parametrized by $\mathbf{r}(t) = \langle t^2, t^2, \frac{1}{3}t^3 \rangle$ for $0 \le t \le 1$.

1a(8 pts).(Source: 12.6.14,18) It helps to consider the cross-sections of this surface along planes where one variable is constant. When y or z is a constant, the cross-section is a hyperbola that opens in the $\pm x$ direction. When x is a constant, the cross section is a circle if $x^2 \ge 8$ and does not exist otherwise.

The graph is a hyperbola of two sheets. Here's a nice drawing by Mathematica. The positive x, y, and z directions in this figure are up, down-and-left, and down-and-right. Because xcan't equal zero in the equation $x^2 - y^2 - z^2 = 8$, the surface misses the yz-plane.

1b.(Source: 12.6.36,12.1.17-20) Rewrite the equation in 1b by completing the square.

$$x^{2} - 6x - y^{2} - 4y - z^{2} = 3$$
$$x^{2} - 6x + 9 - y^{2} - 4y - 4 - z^{2} = 3 + 9 - 4$$
$$(x - 3)^{2} - (y + 2)^{2} - z^{2} = 8$$

This graph is obtained by shifting the graph in 1a 3 units in the positive x direction and 2 units in the negative y direction.

2a.(Source: 12.1.23) The radius of the sphere is the distance from the point (-2, 1, 3) to the yz-plane, or 2, so the equation is $(x+2)^2 + (y-1)^2 + (z-3)^2 = 2^2$.

2b.(Source: 12.5.12) We need a point on the line and vector parallel the line. You can find two points on the line by picking an arbitrary value for x and solving the two given equations for y and z. In this way, I found (0, 1, 1) and (1, 0, -2). The vector between these points, $\langle 1, -1, -3 \rangle$, is parallel to the line. Using this vector and the first point, parametrize the line by $\langle t, 1 - t, 1 - 3t \rangle$.

2c.(Source: 12.5.35) We need a point on the plane and vector orthogonal to the plane. To find the vector, observe that the line is parallel $\langle -1, 3, -2 \rangle$ and passes through the point (1, 1, 0). The plane is parallel both $\langle -1, 3, -2 \rangle$ and the vector between our two points, $\langle 0, 1, 0 \rangle$. Therefore, their cross-product

$$\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -1 & 3 & -2 \\ 0 & 1 & 0 \end{vmatrix} = \mathbf{i} \begin{vmatrix} 3 & -2 \\ 1 & 0 \end{vmatrix} - \mathbf{j} \begin{vmatrix} -1 & -2 \\ 0 & 0 \end{vmatrix} + \mathbf{k} \begin{vmatrix} -1 & 3 \\ 0 & 1 \end{vmatrix} = \langle 2, 0, -1 \rangle$$

is orthogonal to the plane. Using this vector and the point (1, 1, 0), obtain the equation 2(x-1) - z = 0.



2d.(Source: 13.1.32) Substitute x = 2t, $y = \sin(\pi t)$, and $z = \cos(\pi t)$ into $x^2 - y^2 - z^2 = 8$ and solve for t:

$$4t^{2} - \sin^{2}(\pi t) - \cos^{2}(\pi t) = 8 \implies 4t^{2} - 1 = 8 \implies t^{2} = \frac{9}{4} \implies t = \pm \frac{3}{2}$$

Find the points of intersection by evaluating the parametrization at these *t*-values. At $t = \frac{3}{2}$, the point is $\left(2 \cdot \frac{3}{2}, \sin(\frac{3}{2}\pi), \sin(\frac{3}{2}\pi)\right) = (3, -1, 0)$. At $t = -\frac{3}{2}$, the point is (-3, 1, 0). 2e.(Source: 13.2.23-26) The line passing through the point (1, 2, 0) and parallel to $\langle 0, 3, 4 \rangle$ can be parametrized by $\langle 1, 2 + 3t, 4t \rangle$.

3a(4 pts).(Source: 13.4.9)

$$\frac{d\mathbf{r}}{dt} = \mathbf{r}' = \langle 2t, 2t, t^2 \rangle = \langle -2, -2, 1 \rangle \text{ at } t = -1$$
$$\frac{d^2\mathbf{r}}{dt^2} = \mathbf{r}'' = \langle 2, 2, 2t \rangle = \langle 2, 2, -2 \rangle \text{ at } t = -1$$

3b(13 pts).(Source: 13.3.47) $\mathbf{T} = \frac{1}{|\mathbf{r}'|}\mathbf{r}' = \frac{1}{3}\langle -2, -2, 1 \rangle$. To find **B**, normalize

$$\mathbf{r}' \times \mathbf{r}'' = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ -2 & -2 & 1 \\ 2 & 2 & -2 \end{vmatrix} = \mathbf{i} \begin{vmatrix} -2 & 1 \\ 2 & -2 \end{vmatrix} - \mathbf{j} \begin{vmatrix} -2 & 1 \\ 2 & -2 \end{vmatrix} + \mathbf{k} \begin{vmatrix} -2 & -2 \\ 2 & 2 \end{vmatrix} = \langle 2, -2, 0 \rangle,$$

(or, more simply, normalize $\langle 1, -1, 0 \rangle$) to obtain $\mathbf{B} = \frac{1}{\sqrt{2}} \langle 1, -1, 0 \rangle$. Finally,

$$\mathbf{N} = \mathbf{B} \times \mathbf{T} = \frac{1}{3\sqrt{2}} \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & -1 & 0 \\ -2 & -2 & 1 \end{vmatrix} = \frac{1}{3\sqrt{2}} \left(\mathbf{i} \begin{vmatrix} -1 & 0 \\ -2 & 1 \end{vmatrix} - \mathbf{j} \begin{vmatrix} 1 & 0 \\ -2 & 1 \end{vmatrix} + \mathbf{k} \begin{vmatrix} 1 & -1 \\ -2 & -2 \end{vmatrix} \right)$$
$$= \frac{1}{3\sqrt{2}} \langle -1, -1, -4 \rangle$$

3c(4 pts).(Source: 13.3.21-23) $\kappa = \frac{|\mathbf{r}' \times \mathbf{r}''|}{|\mathbf{r}'|^3} = \frac{2\sqrt{2}}{3^3}$ 3d(8 pts).(Source: 13.4.41,42) If θ is the angle between \mathbf{r}' and \mathbf{r}'' , then

$$a_T = |\mathbf{r}''| \cos \theta = \frac{\mathbf{r}' \cdot \mathbf{r}''}{|\mathbf{r}'|} = \frac{-10}{3} \qquad a_N = |\mathbf{r}''| \sin \theta = \frac{|\mathbf{r}' \times \mathbf{r}''|}{|\mathbf{r}'|} = \frac{2\sqrt{2}}{3}$$

 $\begin{array}{ll} 4a(2 \ \mathrm{pts}).(\mathrm{Source:} \ 12.2.22) & 2\mathbf{u} - \mathbf{v} = \langle 2, -4, 4 \rangle - \langle 3, 6, 2 \rangle = \langle -1, -10, 2 \rangle. \\ 4b(2 \ \mathrm{pts}).(\mathrm{Source:} \ 12.2.22) & |\mathbf{u}| = \sqrt{1^2 + (-2)^2 + 2^2} = \sqrt{9} = 3. \\ 4c(2 \ \mathrm{pts}).(\mathrm{Source:} \ 12.2.23-25) & \frac{1}{|\mathbf{u}|}\mathbf{u} = \frac{1}{3}\langle 1, -2, 2 \rangle, \ \mathrm{or} \ \langle \frac{1}{3}, -\frac{2}{3}, \frac{2}{3} \rangle. \\ 4d(6 \ \mathrm{pts}).(\mathrm{Source:} \ 12.3.17-18) & |\mathbf{v}| = \sqrt{9 + 36 + 4} = 7, \ \mathrm{and} \ \cos\theta = \frac{\mathbf{u} \cdot \mathbf{v}}{|\mathbf{u}||\mathbf{v}|} = \frac{3-12+4}{3\cdot7} = \frac{-5}{21}. \\ 4e(4 \ \mathrm{pts}).(\mathrm{Source:} \ 12.3.41-42) & \mathrm{proj}_{\mathbf{v}} \mathbf{u} = \frac{\mathbf{v} \cdot \mathbf{u}}{\mathbf{v} \cdot \mathbf{v}} \mathbf{v} = \frac{-5}{49}\langle 3, 6, 2 \rangle. \end{array}$

5(11 pts). (Source: 13.3.5) Arclength $s = \int \frac{ds}{dt} dt = \int \left| \frac{d\mathbf{r}}{dt} \right| dt =$

$$\int_0^1 \sqrt{4t^2 + 4t^2 + t^4} \, dt = \int_0^1 \sqrt{8t^2 + t^4} \, dt$$
$$= \int_0^1 \sqrt{(t^2)(8 + t^2)} \, dt = \int_0^1 t \sqrt{(8 + t^2)} \, dt$$

To integrate, substitute $u = 8 + t^2$, so that du = 2t dt, or $\frac{1}{2} du = t dt$. New limits are u = 8 (when t = 0) and u = 8 (when t = 1). The integral becomes

$$\int_{8}^{9} \frac{1}{2} u^{1/2} \, du = \frac{1}{3} u^{3/2} \Big|_{8}^{9} = \frac{1}{3} (9^{3/2} - 8^{3/2}).$$