

1. Let $G = \begin{bmatrix} 1 & 1 & -1 & -5 \\ 4 & 2 & 2 & -22 \\ 1 & 4 & -10 & -1 \end{bmatrix}$. and $\mathbf{p} = \begin{bmatrix} 2 \\ 0 \\ -3 \\ -1 \end{bmatrix}$.

a (2 pts). Calculate the product $G\mathbf{p}$ or explain why it does not exist.

b (6 pts). Express the solution(s) to $G\mathbf{x} = \mathbf{0}$ in parametric form.

c (2 pts). How many solutions are there to $G\mathbf{x} = \begin{bmatrix} 10 \\ 24 \\ 33 \end{bmatrix}$? Explain.

Solution:

1b.(Source: 1.4.11-12,1.5.6-12) To solve the homogeneous system, row reduce G . There's no need to augment the zero column $\mathbf{0}$ if we remember that it's unchanged by row operations.

row operation	result
initial matrix	$\begin{bmatrix} 1 & 1 & -1 & -5 \\ 4 & 2 & 2 & -22 \\ 1 & 4 & -10 & -1 \end{bmatrix}$
$\mathbf{r}_2 \leftarrow \mathbf{r}_2 - 4\mathbf{r}_1$ $\mathbf{r}_3 \leftarrow \mathbf{r}_3 - \mathbf{r}_1$	$\begin{bmatrix} 1 & 1 & -1 & -5 \\ 0 & -2 & 6 & -2 \\ 0 & 3 & -9 & 4 \end{bmatrix}$
$\mathbf{r}_2 \leftarrow -\frac{1}{2}\mathbf{r}_2$	$\begin{bmatrix} 1 & 1 & -1 & -5 \\ 0 & 1 & -3 & 1 \\ 0 & 3 & -9 & 4 \end{bmatrix}$
$\mathbf{r}_3 \leftarrow \mathbf{r}_3 - 3\mathbf{r}_2$	$\begin{bmatrix} 1 & 1 & -1 & -5 \\ 0 & 1 & -3 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$
$\mathbf{r}_2 \leftarrow \mathbf{r}_2 - \mathbf{r}_3$ $\mathbf{r}_1 \leftarrow \mathbf{r}_1 + 5\mathbf{r}_3$	$\begin{bmatrix} 1 & 1 & -1 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$
$\mathbf{r}_1 \leftarrow \mathbf{r}_1 - \mathbf{r}_2$	$\begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

Solution in ...

parametric form:

$$\begin{aligned}x_1 &= -2x_3 \\x_2 &= 3x_3 \\x_3 &= \text{free} \\x_4 &= 0\end{aligned}$$

parametric vector form:

$$\mathbf{x} = s \begin{bmatrix} -2 \\ 3 \\ 1 \\ 0 \end{bmatrix}.$$

1a.(Source: 1.4.5)

$$\begin{aligned}G\mathbf{p} &= \begin{bmatrix} 1 & 1 & -1 & -5 \\ 4 & 2 & 2 & -22 \\ 1 & 4 & -10 & -1 \end{bmatrix} \begin{bmatrix} 2 \\ 0 \\ -3 \\ -1 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 4 \\ 1 \end{bmatrix} + 0 \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix} - 3 \begin{bmatrix} -1 \\ 2 \\ -10 \end{bmatrix} - \begin{bmatrix} -5 \\ -22 \\ -1 \end{bmatrix} \\ &= \begin{bmatrix} 2 \\ 8 \\ 2 \end{bmatrix} + \mathbf{0} + \begin{bmatrix} 3 \\ -6 \\ 30 \end{bmatrix} + \begin{bmatrix} 5 \\ 22 \\ 1 \end{bmatrix} = \begin{bmatrix} 10 \\ 24 \\ 33 \end{bmatrix}\end{aligned}$$

1c.(Source: 1.2.19, 1.5.19-20) The vector \mathbf{p} is a solution to $G\mathbf{x} = \begin{bmatrix} 10 \\ 24 \\ 33 \end{bmatrix}$. By Theorem 6, p.

49, the solutions to $G\mathbf{x} = \begin{bmatrix} 10 \\ 24 \\ 33 \end{bmatrix}$ are all vectors of the form $\begin{bmatrix} 2 \\ 0 \\ -3 \\ -1 \end{bmatrix} + s \begin{bmatrix} -2 \\ 3 \\ 1 \\ 0 \end{bmatrix}$. Therefore,

there are infinitely many solutions to $G\mathbf{x} = \begin{bmatrix} 10 \\ 24 \\ 33 \end{bmatrix}$.

1c. Alternate solution. \mathbf{p} is a solution to $G\mathbf{x} = \begin{bmatrix} 10 \\ 24 \\ 33 \end{bmatrix}$, so the system has at least one

solution. Since G contains a free variable, $G\mathbf{x} = \begin{bmatrix} 10 \\ 24 \\ 33 \end{bmatrix}$ must have infinitely many solutions.

(done)

Comment: 1c. A free variable in a *consistent* system implies that the system has infinitely many variables, but the presence of a free variable does not by itself imply that a nonhomogeneous system has infinitely many variables. In 1c., it's important to note that

part a. shows that $G\mathbf{x} = \begin{bmatrix} 10 \\ 24 \\ 33 \end{bmatrix}$ has a solution.